2019 Netval Summer Conference September 18, 2019 CNR, Rome, Italy

Biomedical Technologies for Clinical Innovation

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The cerebral ventricles in Leonardo's anatomical drawings

evidence.

Based on arabic and medieval medical sources (1490)



According to the Aristotelian theory of soul, the three ventricles are the sites of sensation, reason, and memory. This drawing is a perfect example of so-called theory-loaded knowledge.

The refined anatomical knowledge of the brain, combined with further knowledge regarding cranial nerves (auditory and trigeminal) obtained through this procedure, led Leonardo to abandon the functional theory not supported by this newly acquired empirical



Based on innovative experimental method (1504–07)



Leonardo's wax injection method clearly shows that scientific progress is often driven by revolutionary uses of existing tools rather than by groundbreaking ideas.

Di Stefano, N., Ghilardi, G., & Morini, S. (2019). The cerebral ventricles in Leonardo's anatomical drawings. The Lancet, 393(10179), 1412.

FAST – Institute of Philosphy of Science and Technology – Università Campus Bio-Medico di Roma



Innovation forecasting is challenging....





1982 (based on P. Dick's novel published in 1969)

Martin Cooper, Motorola. 1973



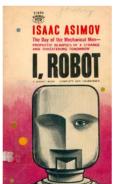




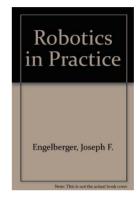
















The Future of Medicine

1.0 Symptom-based *Intuition medicine*



Interaction-based Medicine

Stethoscope



Theophile Hyacinthe Laennec (1816)

L. BORGHI, A. ONETTI MUDA, Università Campus Bio-Medico di Roma La bioingegneria per il benessere e l'invecchiamento attivo, M.C. Carrozza, E. Guglielmelli, R. Pietrabissa, Patron Editore 2016



The Future of Medicine

1.0 Symptom-based *Intuition medicine*

2.0 Interaction-based *Measure medicine*



The Future of Medicine

1.0 Symptom-based *Intuition medicine*

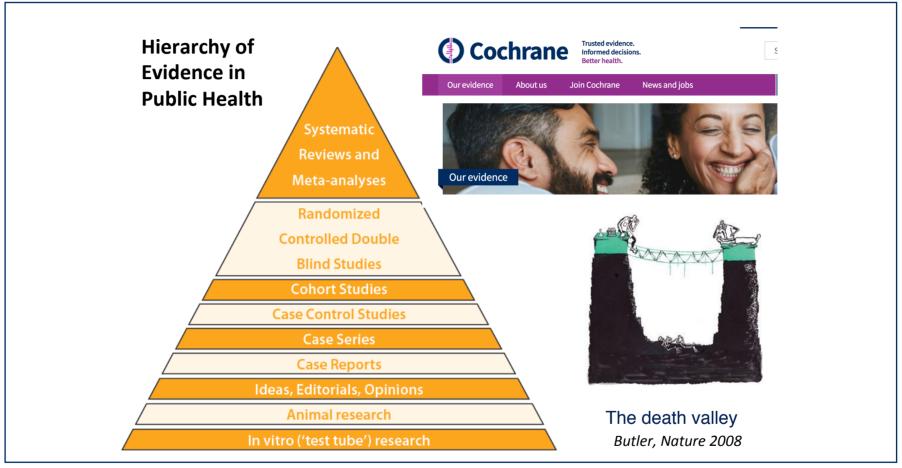
2.0 Interaction-based *Measure medicine*

3.0

Pattern-based *Evidence medicine*



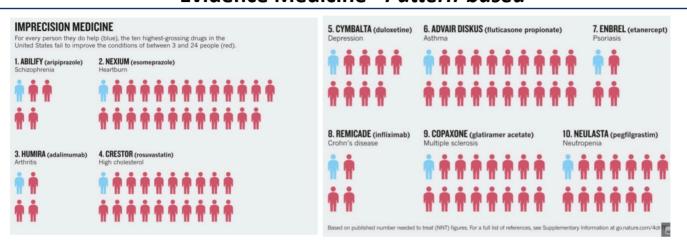
Evidence Medicine - Pattern-based





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Evidence Medicine - Pattern-based



Personalized medicine: Time for one-person trials

Nicholas J. Schork

29 April 2015

Precision medicine requires a different type of clinical trial that focuses on individual, not average, responses to therapy, says Nicholas J. Schork.



Time for one-person trials

Precision medicine requires a different type of clinical trial that focuses on



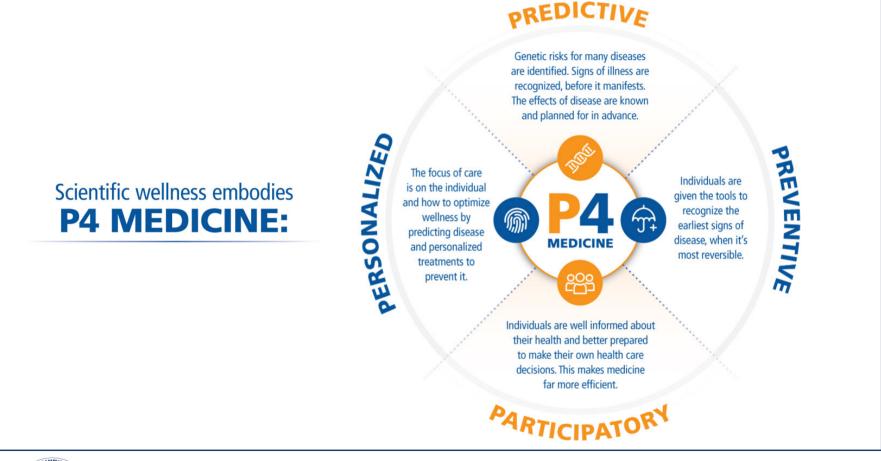
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ein an alboc wije Fre instance, a doctor or even the population at large.



The Future of Medicine





The Future of Medicine

1.0 Symptom-based *Intuition medicine*

2.0 Interaction-based *Measure medicine*

3.0

Pattern-based Evidence medicine



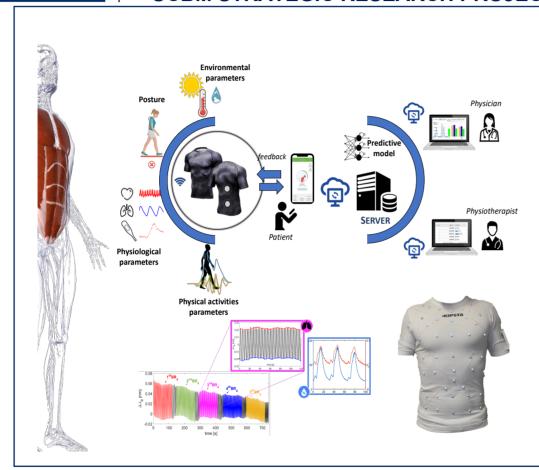


4.0

Algorithm-based 4P medicine



UCBM STRATEGIC RESEARCH PROJECT - HEALTHCARE 4.0



BIOMEDICAL BIG DATA

- ✓ Wearable system for the continuous monitoring of physiological parameters
- ✓ Environmental conditions monitoring
- ✓ Real-time data collection and storage
- ✓ Human-computer interfaces (HCI)
 to assess the patient's progress and
 to enhance the patient's
 engagement



Breathing rate Breathing volumes



Breathing biomechanics





Magnetic resonance compatible



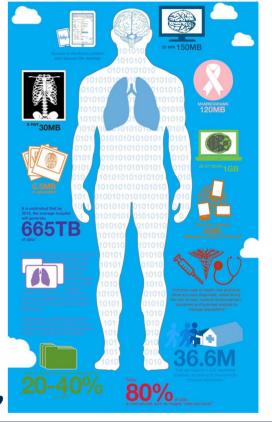
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Al for personalized medicine - Radiomics



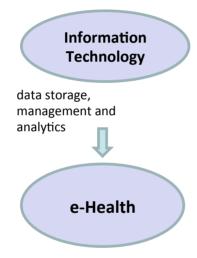
- Integration of
 - Pathomics, Genomics, Phenomics and Exposome Data
 - Images routinely collected in cancer diagnosis and treatment to
 - 1. Forecast tumour prognosis
 - 2. Clinical decision personalization
 - 3. Treatment selection
 - 4. Update treatment plans

Joint Laboratory on Precision Medicine and BioData Analytics Università Campus Bio-Medico di Roma & Centro Diagnostico Italiano



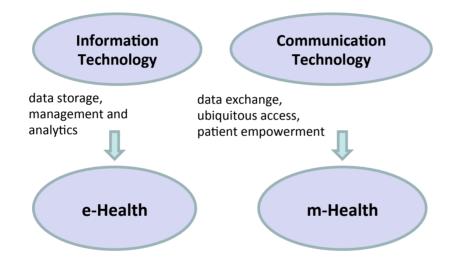


Evolution of Enabling Technologies for Innovation in Healthcare



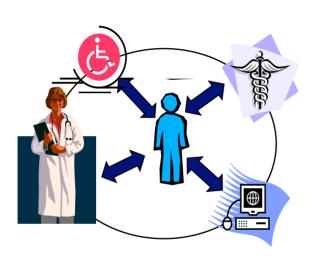


Evolution of Enabling Technologies for Innovation in Healthcare





Mobile Health - Ubiquitous Medicine



- Patient awareness and empowerment
- ICT-based services
- Self-administered assessment and therapy
- Early discharge of patients at home
- Home\Remote delivery of therapy to reduce treatment-related mobility costs
- Lack of spaces where delivering therapy



BRAIN INNOVATIONS SRL - «CAMPUS BIO-MEDICO DI ROMA» UNIVERSITY SPIN-OFF (Lazzaro Di Biase, MD, PhD Student in Neurology)



Il progetto è stato premiato da Zcube con un finanziamento di 25 mila euro



BRAIN INNOVATIONS proposes complete solution that addresses all the needs of Parkinson's Disease patients with the following instruments:

- Answer to PD Diagnosis device
- Answer to PD Symptoms monitoring device
- PD Assistant Oral Therapy device
- PD Assistant Infusional therapy device



ICONE

The only *all-in-one* & *plug-and-play* rehabilitation system









I Can Robotics

- Enabling home rehabilitation scenarios
- · Portable, low weight and size
- Better interactive performance with patients Performance evaluation

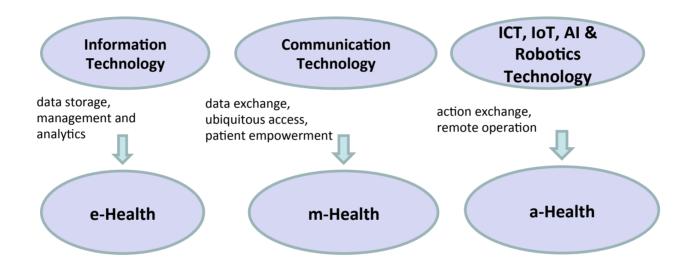
(patent pending)

heaxel

Heaxel is a newco of ICan Robotics & VERTIS SGR, the 1st spin-off accredited by UCBM www.haexel.com



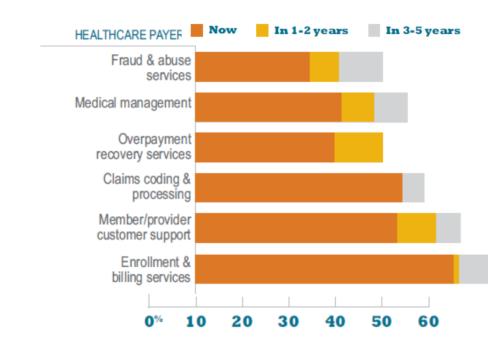
Evolution of Enabling Technologies for Innovation in Healthcare



From electronic-Health and mobile-Health to...... automated-Health



Managing Health and Care In the Digital Age



RPA
Robotic
Process
Automation

Percent of process automation as gauged by workflow

The Robot and I: How New Digital Technologies Are Making Smart People and Businesses Smarter by Automating Rote Work, Cognizant Report, 2015



Robotic systems for service applications in hospitals



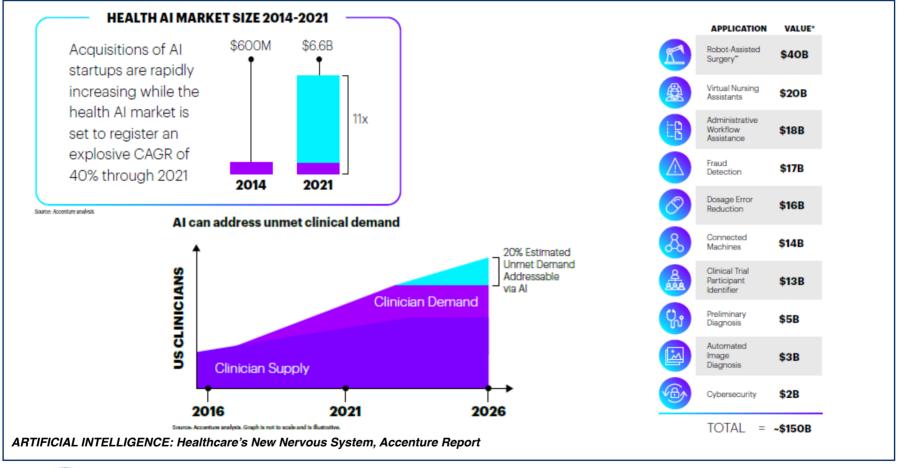






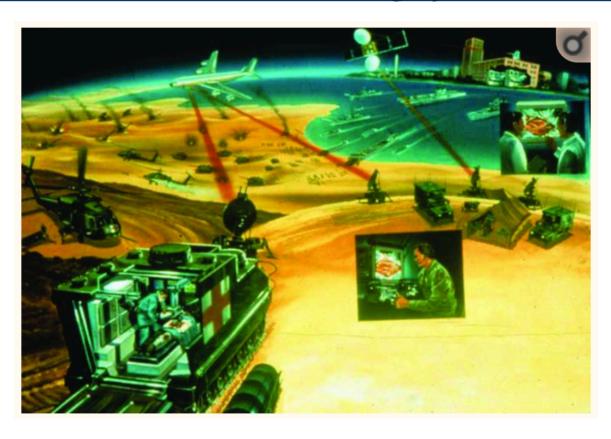


Health Al Market





Robot-assisted Surgery





Robot-assisted Surgery





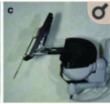


Figure 8.

Lenny, Mona, and da Vinci patient-side manipulators.







Figure 9.

Lenny, Mona, and da Vinci master controllers.



JSLS. 2018 Oct-Dec; 22(4): e2018.00039. doi: 10.4293/JSLS.2018.00039 PMCID: PMC6261744 PMID: 30524184

Origins of Robotic Surgery: From Skepticism to Standard of Care

Evalyn I. George, BS, COL Timothy C. Brand, MD, COL (Ret) Anthony LaPorta, MD, Jacques Marescaux, MD, and COL (Ret) Richard M. Satava, MD^{III}



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Robot-assisted Surgery

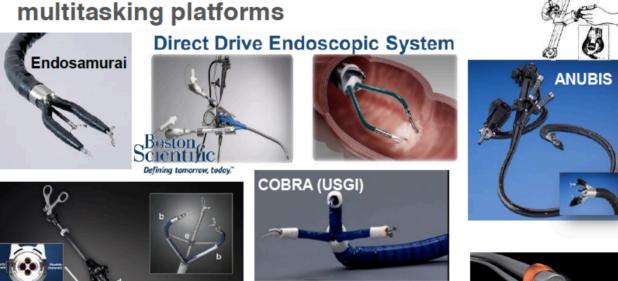


An example setup of the da Vinci Si system. (Image credit: Intuitive Surgical Inc.)



Surgical Robotics

NOTES: flexible endoscopic multitasking platforms

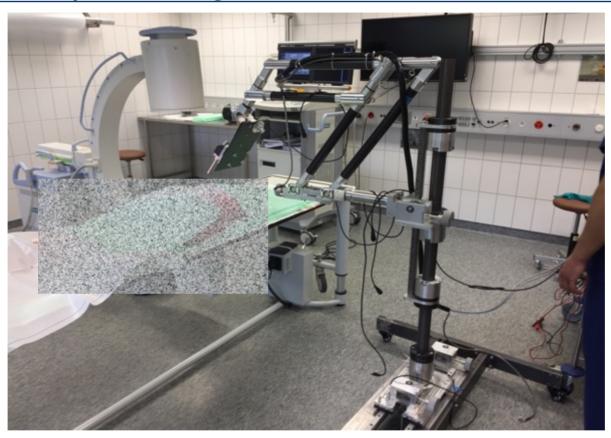


Endovia



SPIDER surgical system

Co-operative Surgical Robots



CADAVER TEST: May 24th-25th, 2018

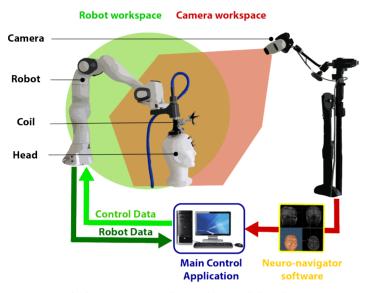
I.Portaccio, G. Vadalà, D. Accoto et al., UCBM, BIOROB 2016



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NEXT LAB - Neurophysiology and Neuroengineering of Human-Technology Interaction

Robot-aided Transcranial Magnetic Stimulation



- High accuracy in coil positioning
- High repeatability stimulating the same site
- Automatic hot-spot identification
- Head motion compensation



- High stiffness in stimulation plane → high accuracy
- Compliant behavior perpendicular to the head → safety and comfort for the subject





BIO-COOPERATIVE ROBOTIC SYSTEMS FOR REHABILITATION



Final prototype tested on a patient affected by SLA $\mathbf{3x}$



Robotic arm controlled by subjects with Spinal cord injury



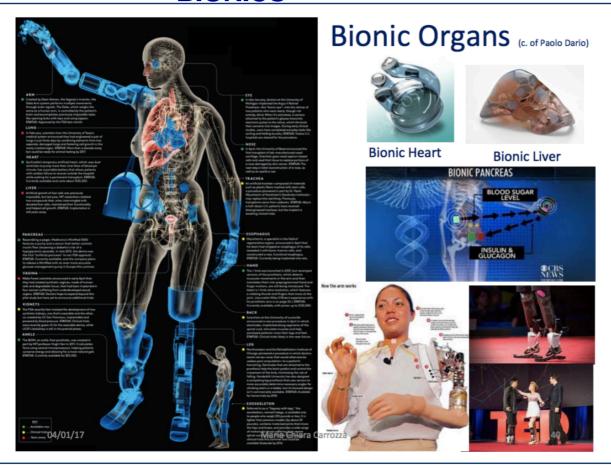


Crea S., Nann M., Trigili E., Cordella F., Baldoni A., Badesa F.J., Catalán, J.M., Zollo L., Vitiello N., Aracil N.G., Soekadar S.R., "Feasibility and safety of shared EEG/EOG and vision-guided autonomous whole-arm exoskeleton control to perform activities of daily living", Scientific Report, vol.8, no.1, 2018.

Lauretti C., Cordella F., Ciancio A.L., Trigili E., Catalan J.M., Badesa F.J., Crea S., Pagliara S.M., Sterzi S., Vitiello N., Aracil N.G., Zollo L., "Learning by demonstration for motion planning of upper-limb exoskeletons", Frontiers in Neurorobotics, 2018



BIONICS









Science Robotics





PPR2 project: Control of upper-limb prosthesis with neural invasive interfaces

To recover <u>sensorimotor integration</u> through neural electrodes and to enable real-time closed-loop control of bionic hands in tasks of <u>fine grasp and manipulation</u>, by using routed sensory information.



L. Zollo, et al., E. Guglielmelli, Restoring tactile sensations via neural interfaces for real-time force-and-slippage closed-loop control of bionic hands. Science Robotics 4, eaau9924 (2019).



Increasing complexity and improvement over time

Lateral grasp



Pick and place with Power grasp



Pick and place with Precision grasp



Manipulation task



Task complexity

- · Improvement of grasping and manipulation capabilities over time
- · Interoperability: one research prototype and one commercial hand.

L. Zollo, et al.. Science Robotics 4, (2019).

Manipulation task with neural feedback (commercial prosthesis)



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Market Trends









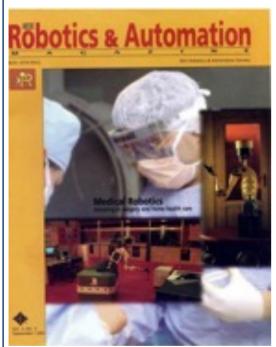


- The **Medical Robots** market is projected to reach USD 12.80 billion by 2021 from USD 4.90 billion in 2016, growing at a CAGR of 21.1% during the forecast period.
- In 2016, the **Surgical Robots** segment commanded the largest share of medical robot systems. However, the **Rehabilitation Robot** systems are likely to grow at the highest CAGR during the forecast period.
- The global **Medical Robotics & Bionics** market was valued at USD 15,348 million in 2016, and is expected to garner USD 29,160 million by 2023, registering a CAGR of 9.6% during the forecast period.

Fonti: http://www.marketsandmarkets.com/Market-Reports/medical-robotic-systems-market-2916860.html https://www.alliedmarketresearch.com/medical-bionics-market

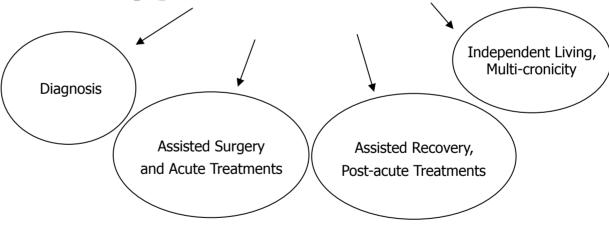


IEEE Robotics & Automation Magazine, Vol. 3, No. 3, 1996





Robotics for Medical Applications















IEEE TRANSACTIONS ON

MEDICAL ROBOTICS AND BIONICS

A PUBLICATION OF THE IEEE ROBOTICS AND AUTOMATION SOCIETY THE IEEE ENGINEERING IN MEDICINE AND BIOLOGY SOCIETY

VOLUME 1





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EDITORIAL

Medical Robotics and Bionics: A New Interdisciplinary Adventure

[GIEST EDITORIAL]

A Perspective of BioRobotics From the IEEE RAS/EMBS BioRob 2018 Conference

[S. Misra and H. van der Kooij]

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PAPIES

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Reconstructing Tisue Properties From Medical Images With Application in Cancer Screening

[S. Ximg. J. Linng, V. Jojic. J. Linn, R. C. Chen, and M. C. Lin

[On the Use of a Continuum Manipulator and a Bendable Medical Screen for Minimally Juvawie Interventions in Orthopodic

Surgery

[F. Alambeigt, M. Balshintinejad, S. Sefan, R. Hegeman, I. Iordachita, H. Khamja, and M. Armand

Famicular Flexible Crawler for Colonoscopy

Preliminary Validation of a Cable-Driven Powered Ankle-Foot Orthosis With Daal Actuation Mode

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A Kone-Ankle-Foot Orthosis to Assist the Sound Limb of Transfermenal Armputees

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Concerted Courted of Stance and Balance. Locomoror Submicricions—Leg Free as a Conductor

[S. Summadi, C. Schumacher, A. Sepfarth, and M. A. Sarbridg]

Estimation of Phantom Arm Mechanics About Four Degrees of Freedom After Targeted Musck Reinnervation

[M. Sartori, J. van de Riet, and D. Farina

[S. Summadi, C. Schumacher, A. Sepfarth, and M. A. Sharbaff

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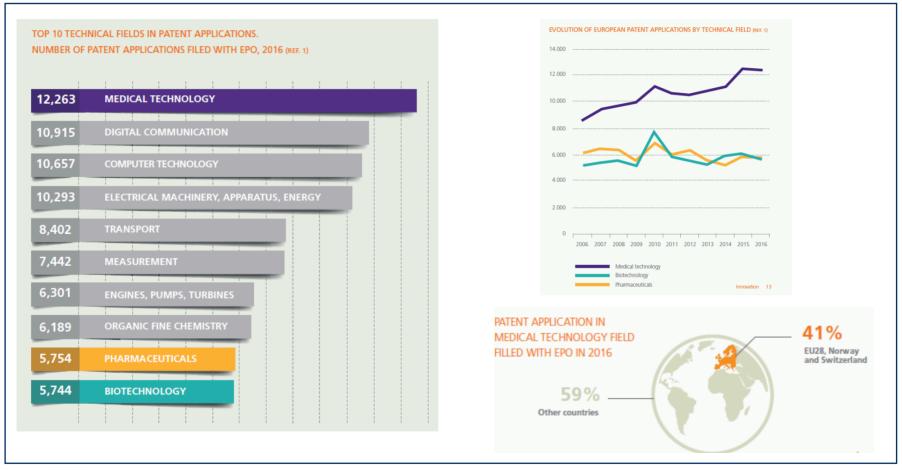
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The European Medical Technology Industry - in figures / 2018, MedTech Europe, www.medtecheurope.org

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Thank you!

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Member, Steering Committee of the Stakeholder Board, Human Brain FET Flagship Project

Vice-President for Publication Activities IEEE Robotics and Automation Society



Founding Editor-in-Chief Springer Series on Biosystems and Biorobotics





